

3 STOLOV, R. M.

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ATTN: 2755
1/07/60/004/01/001/01
0015/004

Elmshik, V. A., Zverev, B. P., Kozlov, V. G.,
Mikhailov, A. M., Mironov, E. A., Shatalov, E. V., and
Stolov, R. M.

TITLE: An Investigation of the Electric and Magnetic Discharge
Characteristics of "Alfa" Research Installation

PERIODICAL: Zhurnal Tekhnicheskoy Fiziki, 1960, Vol. 30, No. 12,
pp. 1408 - 1416

NOTE: The authors studied the electric and magnetic discharge charac-
teristics under single-period conditions. The total discharge current
is measured by means of a Rogowski coil, having the shape of a
spiral made of aluminum. The signal was integrated in an RC circuit.
In the case of the two channels of a double-beam oscilloscope. In a
similar manner, the field strength of the rotational field was measured.
According to voltage and current oscillations the mean resistance of the
discharge column and the energy generated in it were calculated. A somewhat
laboratory of the discharge cell being assessed. Accordingly, the

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Discharge column has an inductivity of $(2-3) \cdot 10^{-6}$ henries. Furthermore,
an electron- and ion temperature of about $40 \cdot 10^4$ K was obtained with
a pressure of $2 \cdot 10^{-4}$ mm Hg and a discharge energy of about 100 eV.
The distribution of the magnetic field over the cross section
of the chamber was determined with probes. The results obtained are
graphically represented in Fig. 9. It was found that the electric cur-
rent lines in the discharge are of helical character similar to the
shape of the magnetic field, which leads to an increase of the longi-
tudinal magnetic field in the chamber. In order to measure current
density, it is necessary that rotational magnetic field be measured in the
shell of the outer chamber. This leads to a change in the field direc-
tion and in the space between outer and inner chamber. The singly
measured increase of the field strength of the longitudinal magnetic
field corresponds to a maximum azimuthal current in the plasma of
 $(2-3) \cdot 10^8$ A. Exactly this current must be induced in the shell of

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The outer chamber. From an analysis of the distribution curves of the
magnetic field and the discharge current, it is found that the density
vector of the electric current has a direction over the total discharge
cross section, which nearly coincides with the direction of the magnetic
field. Further, some experimental conditions were determined, under which
the discharge current in the outer regions of discharge has a direction
inverse to the discharge current in the inner regions. There are 11 fig-
ures, 7 tables, and 6 Soviet references.

ABSTRACT: Research-Leningrad, only Institute of Electrodynamics
apparatus (Scientific Research Institute of Electro-
Physical Apparatus)

DATE: July 13, 1960

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87157

S/057/60/030/012/004/011
B019/B056

26.2311

AUTHORS: Burtsev, V. A., Stolov, A. M., Shakhov, V. V.
TITLE: Measurement of the Energy Flux Emitted by Plasma in
"Al'fa" Research Installation
PERIODICAL: Zhurnal tekhnicheskoy fiziki, 1960, Vol. 30, No. 12,
pp. 1415 - 1421

TEXT: For measuring the energy emitted from the walls of the discharge chamber, a spherical black body with a low thermal capacity and an absorption coefficient of nearly unity was used. By means of this black body only measurements of the total energy emission could be made, because its time lag was too great. For measuring the time dependence of the energy fluxes, a plane pickup (bismuth thermocouple) was used. The signals of the two pickups were made visible by an oscilloscope. The measurements showed that the apparatus used here records not only that part of the energy which is introduced into the plasma. It is assumed that by arc discharges a considerable part of energy is liberated by local emissions, and also a loss occurs as a result of oscillations of

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Measurement of the Energy Flux Emitted by
Plasma in "Al'fa" Research Installation

87457
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B019/B056

the magnetic field of discharge. The recorded energy emission practical-ly begins with a considerable lag relative to the beginning of discharge. The authors thank B. P. Konstantinov for the suggestion to use a black body for the measurements, and they also thank L. M. Andrezen and L. I. Zantova of the chemical laboratory for their help in producing the pickups. There are 7 figures and 4 Soviet references.

ASSOCIATION: Nauchno-issledovatel'skiy institut elektrofizicheskoy apparatury (Scientific Research Institute of Electro-physical Apparatus)

SUBMITTED: July 15, 1960

Card 2/3

Card 3/3

h0739

S/120/62/000/004/004/047
E194/E420

AUTHORS: Monoszon, N.A., ~~Stolov, A.M.~~, Gashev, M.A.,
Spevakova, F.M., Yavno, A.Kh., Kornakov, Ye.V.,
Kulakov, F.M., Nadgornyy, V.P., Gorshkova, Ye.G.

TITLE: The supply system for the electromagnet of a proton-
synchrotron of 7 Gev

PERIODICAL: Pribory i tekhnika eksperimenta, no.4, 1962, 27-33

TEXT: The article describes the supply system for an electro-
magnet, the field of which increases at the steady rate of
 6.7×10^3 Oe/sec to reach a maximum value of 9300 Oe in 1.55 sec
and then falls off exponentially in 0.8 sec, the repetition
frequency is 10 to 12 cycles per minutes. The voltage on the
electromagnet is increased from 5000 to 10250 V with a maximum
current of 2500 A. An induction motor of 3500 kW, 6 kV,
740 rpm drives through a fluid coupling a 6 phase alternator of
peak output 37500 kW, 8.2 kV, and an auxiliary generator of
250 kW, 380 V for auxiliary supply to the 12-phase ignitron
rectifier. During the current decrement period the rectifier
operates as an inverter. A description of the smoothing circuit
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The supply system for the electro-...

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E194/E420

is given. Particular fault conditions of the circuit are analysed and the protective devices fully described. The performance is illustrated by oscillograms. Schematic and block circuit diagrams are given and an outline drawing of the ignitrons. There are 8 figures.

ASSOCIATION: Nauchno-issledovatel'skiy institut elektrofizicheskoy apparatury GKAE (Scientific Research Institute for Electrophysical Apparatus GKAE)

SUBMITTED: April 10, 1962

Card 2/2

04.1732

S/120/62/000/004/031/047
E140/E420

AUTHORS: Monoszon, N.A., Stolov, A.M., Spevakova, F.M.
TITLE: The influence of parasitic parameters of the proton synchrotron electromagnets on the asymmetry of the magnetic field and methods of compensating it

PERIODICAL: Pribory i tekhnika eksperimenta, no.4, 1962, 168-171

TEXT: The strictest requirements on symmetry of the magnetic field occur at the point of injection, where the excitation current is lowest. At the start of each acceleration cycle a constant potential is applied to the electromagnet winding with a fairly steep wavefront. The presence of parasitic conductance and shunt capacitance in the system (Fig.1, equivalent circuit) gives rise to transient asymmetry. The article describes a potentiometric system of correction for these distortions. There are 7 figures.

VB

ASSOCIATION: Nauchno-issledovatel'skiy institut elektrofizicheskoy apparatury GKAE (Scientific Research Institute for Electrophysical Apparatus GKAE)

Card 1/2

STOLOV, P.M.

s/002/00/002/006/003/019
B102/0104

20 700

AUTHORS: Vlasovskiy, V. V., Komar, Ye. G., Mintz, A. L.,
Goldin, I. L., Monozon, N. A., Rubchinskiy, G. M.,
Taranov, Ye. K., Vasil'yev, A. A., Vedop'yantov, F. A.,
Kosharev, D. G., Kuryshov, V. G., Kolyshov, I. F., Stolov,
A. L., Strel'tsov, N. G., Yakovlev, B. M.

TITLE: The design of the 7-Bev proton synchrotron

LITERATURE: Atomnaya energiya, v. 12, no. 6, 1962, 472-474

TEXT: The history of the first Soviet cyclic accelerator with rigid focusing is briefly described, and the most important data on its planning and operation are presented. Planning was started in 1953. The parameters of this proton accelerator, the energy of which exceeds the antineutron production threshold, were so chosen that the dependence of the orbital circumference on the particle momenta was completely compensated. This was achieved by employing 14 quadrupole magnets with orbits of negative curvature. Technical data: output current, 10^{10} protons/pulse; maximum field strength, 8475 oe; length of equilibrium orbit, 251.2 m; radius of
Card 1/2

2/23/62 11/1/62
2106/2104

The design of the 7-bev ...

curvature of the trajectories in the bending magnets (G), 31 m, and in the
compensating magnets (K), 10; number of magnetic sectors, $200 \pm 1\%$; gap
length between the G-magnets, 104.0 cm; gap length around the K-magnets,
117.0 cm; index of the decrease in field strength, 160; internal height
and width of the chamber, 80 and 110 cm, respectively; number of betatron
oscillations per revolution, 12.75, and per periodic element, 0.21;
number of magnets per periodic element, 6; total critical energy, 19.2 Bev;
maximum deviation of the periodic orbit with 100% deviation of the
momentum from the equilibrium momentum, 1.47 m; rate of energy increase
per revolution, 1.3 keV; duration of one cycle, 1.55 sec; 10-12 cycles/min;
particle revolution frequency at the beginning of the cycle, 0.11 Mc/sec,
and at the end, 1.19 Mc/sec; frequency of synchrocyclotron oscillations,
1600 and 150 cps; weight of the electromagnet steel, 2500 tons; maximum
power of the supply system, 25 Mw; Van de Graaff injector (particle energy,
3.0 keV; field strength 20 oe); admissible deviations from field strength
and field gradients, $\sim 10^{-3}$; deviations at the chamber edge due to
nonlinearities, $\sim 10^{-2}$; admissible frequency deviation of the accelerating
field at the beginning of the cycle, 10^{-3} , and at the end, $5 \cdot 10^{-5}$. There
are 1 figure and 1 table.

SUBMITTED: March 12, 1962
Card 2/2

STOLOV, AM

95

8/089/62/013/006/019/027
3102/3106

AUTHORS: G. T. and M. R.

TITLE: Nauchnaya konferentsiya Moskovskogo inzhenerno-fizicheskogo instituta (Scientific Conference of the Moscow Engineering Physics Institute) 1962

PERIODICAL: Atomnaya energiya, v. 13, no. 6, 1962, 603 - 606

TEXT: The annual conference took place in May 1962 with more than 400 delegates participating. A review is given of these lectures that are assumed to be of interest for the readers of Atomnaya energiya. They are following: A. I. Leypunskiy, future of fast reactors; A. A. Vasil'yev, design of accelerators for superhigh energies; I. Ya. Pomeranchuk, analyticity, unitarity, and asymptotic behavior of strong interactions at high energies; A. B. Migdal, phenomenological theory for the many-body problem; Yu. D. Fivovskiy, deceleration of medium-energy antiprotons in matter; Yu. M. Kogan, Ya. A. Izrael'skiy, theory of the Mössbauer effect; M. I. Ryzanov, theory of ionisation losses in nonhomogeneous medium; Yu. B. Ivanov, A. A. Rukhadse, h-f conductivity of subcritical plasma;

Card 1/0

Nauchnaya konferentsiya...

S/089/62/013/006/019/027
B102/B186

B. V. Pletnev, F. M. Spevakov, A. M. Stolov, supply of synchrotron electro-
magnets; G. L. Saksaganskiy, V. Ya. Moiseyev, flanged separable heat-re-
sistant junctions of great diameter; B. G. Klimov, A. S. Vayradyan,
V. F. Yevseyev, I. B. Mikhaylov, I. N. Afonskiy, B. N. Belov, Ye. I, Mamo-
nov, B. I. Strelkov, Ye. V. Sedykh, B. A. Shchukin, optical principles in
computer engineering technique; R. S. Nakhmanson, N. M. Royzin,
M. E. Mostovlyanskiy, Yu. A. Volkov, electronics; Ye. L. Sulim, transmitter
for electromagnetic flow-meter, V. M. Ovsyankin, V. M. Pluzhnikov, applica-
tion of varicondes for transforming d.c. into a.c.

Card 4/A

MONOSZON, N.A.; STOLOV, A.M.; GASHEV, M.A.; SPEVAKOVA, F.M.;
YAVNO, A.Kh.; KORNAKOV, Ye.V.; KULAKOV, F.M.; NADGORNYYI, V.P.;
GORSHKOVA, Ye.G.

Power supply system of the electromagnet of the 7 bev. proton
synchrotron. Prib. 1 tekhn. eksp. 7 no.4:27-33 J1-Ag '62.
(MIRA 16:4)

1. Nauchno-issledovatel'skiy institut elektrofizicheskoy
apparatury Gosudarstvennogo komiteta po ispol'zovaniyu atomnoy
energii SSSR. (Electromagnets) (Synchrotron)

MONOSZON, N.A.; STOLOV, A.M.; SPAVAKOVA, F.M.

Effect of the parasitic parameters of the electromagnet in
a proton synchrotron on the asymmetry of a magnetic field
and methods for its compensation. Prib. i tekh. eksp. 7 no.4:
168-171 J1-Ag '62. (MIRA 16:4)

1. Nauchno-issledovatel'skiy institut elektrofizicheskoy
apparaty Gosudarstvennogo komiteta po ispol'zovaniyu atomnoy
energii SSSR.

(Electromagnets) (Synchrotron)

VLADIMIRSKIY, V.V.; KOMAR, Ye.O.; MINTS, A.L.; GOL'DIN, L.L.;
MONOSZON, N.A.; RUBCHINSKIY, S.M.; TARASOV, Ye.K.; VASIL'YEV, A.A.;
VODOP'YANOV, F.A.; KUSHNARENKO, D.G.; KUKYSHEV, V.S.; MALYSHEV, I.P.;
STOLOV, A.M.; STREL'TSOV, N.S.; YAKOVLEV, B.M.

The 7 bev. proton synchrotron. Prib. i tekhn. eksp. 7 no.4:5-9
J1-Ag '62. (MIRA 16:4)

1. Institut teoreticheskoy i eksperimental'noy fiziki Gosu-
darstvennogo komiteta po ispol'sovaniyu atomnoy energii SSSR,
Nauchno-issledovatel'skiy institut elektrofizicheskoy apparatury
Gosudarstvennogo komiteta po ispol'sovaniyu atomnoy energii
SSSR i Radiotekhnicheskiy institut Gosudarstvennogo komiteta
po ispol'sovaniyu atomnoy energii SSSR.
(Synchrotron)

BOBOVIKOV, R.S.; PLETENEV, B.V.; SPEVAKOVA, F.M.; STOLOV, A.M.

Principles of the construction of resonance systems of supply
of synchrotron electromagnets. Elektrofiz. app. no.2:189-
198 '64. (MIRA 18:3)

L. 47081-65 ENT(m)/ EPA(w)-2/EWA(a)-2 Pub-10/Pt-7 IJP(c) JT/GS
5/0000/64/000/000/0197/0201
ACCESSION NR: AT5007918

AUTHOR: Vladimirov, V. V.; Gol'din, L. L.; Kochkarev, D. G.; Tarasov, Ye. K.;
Yakovlev, B. H.; Guntov, G. K.; Konar, Ye. G.; Kulikov, V. V.; Malyshev, I. F.;
Mamonov, N. A.; Popkovich, A. V.; Stolov, A. M.; Strel'tsov, N. S.; Titov, V. A.;
Vodop'yanov, F. A.; Kuz'min, A. A.; Kuz'min, V. F.; Mints, A. L.; Rubchinakiy,
S. M.; Uvarov, V. A.; Zhadanov, V. M.; Filaretov, S. G.; Shirayev, F. Z.

TITLE: 60-70 Gev Proton Synchrotron

SOURCE: International Conference on High Energy Accelerators. Dubna, 1963. Trudy.
Moscow, Atomizdat, 1964, 197-201

TOPIC TAGS: high energy accelerator, synchrotron

ABSTRACT: A 60-70 Gev proton synchrotron with strong focusing is being constructed
not far from Serpukhov, as has been reported earlier (e.g. "Research Institute for
Electro-Physical Equipment, Leningrad," in Proceedings of the International Confer-
ence on High Energy Accelerators and Instrumentation (CERN, 1959), p. 373). The
present report describes parameter changes and improvements in precision structural
characteristics of the accelerator, and the present state of construction in mid-
1963. The parameters of the magnet are presented in a table. A small change in
the original plans permitted an increase in the length of a part of the free
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L 43038-65

ACCESSION NR: AT5007918

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sections, some of which are utilized for input and exit of beams. The super-period design is described. The lengthened sections were obtained as a consequence of shortening the focusing and defocusing blocks by 112 cm. The focusing properties of the magnetic channel were diminished consequently, but very little; and the limiting energy was lowered by 2-3 Gev. The construction of the magnet is described. Each of the magnetic blocks is divided lengthwise into 5 sub-blocks which are enveloped by the common winding. These sub-blocks consist of laminar two-millimeter silicon steel. These steel sheets were stamped out without subsequent mechanical working, and were subjected to sorting and intermixing in order to smooth out their magnetic characteristics. The sub-blocks are constricted by lateral welded plates without adhesion. Provision was made for windings on the poles in order to correct for pole nonlinearity and for variations in the drop reading. These windings make it possible to introduce artificial quadratic (square) nonlinearity that changes the dependence of the frequency of transverse oscillations during a pulse. In order to correct for straying of the residual field, provision has been made for windings on the yoke in series with the main winding. The sub-blocks must undergo calibration on a magnet stand in order to make correcting systems more precise and to determine the most convenient disposition of the sub-blocks along the ring. The winding of the electromagnet is made of aluminum busbars with hollow cores for cooling water. The length of the busbar is so selected that there would be no

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ACCESSION NR: AT5007918

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welded joints inside the coils. The winding consists of 4 sections, two of which are disposed on the upper pole and two on the lower. The most important characteristics of the electromagnet and power supply system are described in a table. Also described are the vacuum chamber and accelerating field (obtained by 33 paired resonators with ferrite rings, which operate at the 30-th harmonic of revolution and give accelerating potential of 350 kilovolts). The ring tunnel and the general arrangement of the accelerator are shown in figures and described. The building for the injector and portions of the ring tunnel from the injector to the experimental room have been completed in the main and are ready for installation of equipment. This room, in the form of a single-aisle building without internal supports, permits one to work on beams brought into the inner and outer sides. A 90-meter arch covers this room, whose overall length is 150 meters. Provisions have been made for a second experimental room at the southwest part of the ring. Orig. has 4 figures, 2 tables.

ASSOCIATION: Institute teoreticheskoy i eksperimental'noy fiziki GKAE SSSR (Institute of Theoretical and Experimental Physics, GKAE SSSR). (2) Nauchno-issledovatel'skiy institut elektrofizicheskoy apparatury imeni D. V. Yefremova GKAE SSSR (Scientific Research Institute of Electrophysical Apparatus, GKAE SSSR).

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ACCESSION NR: AT5007918

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(3) Radiotekhnicheskiy Institute AN SSSR (Radio Engineering Institute, Academy of Sciences SSSR). (4) Gosudarstvennyy proyektnyy Institut GNAE SSSR (State Planning Institute, GNAE SSSR).

SUBMITTED: 26 May 64

ENCL: 00

SUB CODE: EE, NP

NO REF SOV: 002

OTHER: 001

am
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APPROVED
ACCESSION NR: AP4047415

ber by a vortical electric field, and acts as an equivalent secondary turn of a pulse transformer. The produced plasma pinch is stabilized with a longitudinal magnetic field of a toroidal solenoid, inside which the vacuum chamber is located. The magnetic core of the pulse transformer carries the primary vortical-field winding, the demagnetization winding, and the winding for induction heating. The set-up is fed from special power systems. The electromagnetic system, the power supply, and the vacuum system are described in some detail. The longitudinal field intensity reaches 40 kG. The vortical field values are 250 and 50 V per turn with pulse durations 10 and 50 milliseconds, and with programming of the waveform such as to maintain a constant current in the plasma pinch. The power supply delivers a peak power of 77,000 kW, maximum 7000 A, no-load voltage 11 kV, and stored energy 180 million Joules. The vortical field is fed from four capacitor banks rated 1000 μF at 20 kV, 11,000 μF at 10 kV, 78,000 μF at 5 kV, and 30,000 μF at 5 kV. The capacitor-bank parameters can be varied over a wide range. The vacuum in the liner does

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L 3221-65
ACCESSION NR: AP4047415

not exceed $1-2 \times 10^{-7}$ mm Hg during the interval between gas admission, with the pressure in the outside chamber being $1-2 \times 10^{-6}$ mm Hg. Orig. art. has: 8 figures.

ASSOCIATION: None

SUBMITTED: 23Nov63

ENCL: 00

SUB CODE: NP, ME

NR REF SOV: 000

OTHER: 000

Cord 3/3

L 07191-27 EWIC(1)

ACC NR: AT6031766

SOURCE CODE: UR/3092/66/000/004/0165/0168

AUTHOR: Arkhangel'skiy, F. K.; Stolov, A. M.

28
13+1

ORG: none

TITLE: Use of impact generators²⁵ for producing pulsed magnetic fields with high energy capacity

SOURCE: Moscow. Nauchno-issledovatel'skiy institut elektrofizicheskoy apparatury. Elektrofizicheskaya apparatura, no. 4, 1966, 165-168

TOPIC TAGS: pulsed magnetic field, strong magnetic field

ABSTRACT: An evaluation is made of the energy level delivered by a modern impact generator and a comparison is made of performance and economic data associated with this method and with the method of capacitive storage. The derived expressions for key parameters are applied to the evaluation of two specific impact generators: a Soviet mass produced three-phase impact generator with a cylindrical rotor as well as a special impact generator with eight poles developed by Siemens. The Soviet generator has a peak power of 2500 Mw with a model power of 125-150 Mw while the Siemens generator has a model power of 300 Mw. The analysis shows that in the machine version the value of the stored energy which can be achieved in practice is less than that achieved with capacitive storage. From the standpoint of useful life, the capacitive storage

Card 1/2

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621 116 923 621 311 335 - 22 2120
 Quantitative investigation of fuses for the motor
 supplying asynchronous motors. *Novikov, L. L. Izv. Vuzov
 Fizicheskaya, 17 (No. 11 18 21 (1966) In Russian*
 Thermoplastic fuses of Cu, Pb, Ag and Zn for
 protection of asynchronous motors are discussed in
 detail with special consideration of the size and shape
 of the fuse body and the thermal conductivity of
 the fuse contacts. Motor starting current peaks are
 plotted against starting time, with fuse ratings as
 parameter. A. I.

621 116 925 452 621 318.55 see Abstr. 2144

ABSTRACT METALLURGICAL LITERATURE CLASSIFICATION

U.S. I. S. ... Oct. 20, 1961.

Subject: "The ... and ... of ..."

To: Washington, D.C., Air, 1000 (1000-1000)

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6
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C

71

322. Influence of transient electromagnetic conditions on the dynamics of starting an induction motor. SVETOV, L. I. *Elektrichesk* (No. 6) 34 6 (1966) *At Zhurnal*. — Mathematical investigation of the torque developed in a cage-rotor induction motor under the transient conditions which follow direct switching. It is shown that during the establishment of the steady-state magnetic conditions in the machine, there appear two transient pulsating torques and a braking couple. The former influences the starting conditions over a relatively short range of speed from rest; the braking torque is seldom more than 0.1 of the max. torque due to the steady rotating field. Other minor torques due to transient leakage fluxes are shown to have a very insignificant effect. U. S.

450-554 METALLURGICAL LITERATURE CLASSIFICATION

STOLOV, Docent L. I.

Mbr., Kazan' Aviation Inst., -c1948-c1950-. Cand. Technical Sci. "Action of Transition Electromagnetic Processes on the Starting Dynamics of a Short-Circuited Engine," Elektrichestvo, No. 6, 1948; "Starting Short-Circuited Asynchronous Motors With Reduced Voltage," Prom. Energet., No. 3, 1948; "Concerning Yu. L. Mukosoyev's Article 'An Outdated Standard Retards the Development of the Country's Power Economy,'" Elektrichestvo, No. 6, 1949; "Projected Standard of Nominal Voltages for Stationary Electric Networks," ibid., No. 8, 1950.

STOLOV, L.I.

Transient moments at direct-on starting of asynchronous motors. Trudy
(MIRA 10:6)
KAI 22:31-35 '49. (Electric motors, Induction)

STOLOV, L. I., Docent

PA 167T34

USSR/Electricity - Standards, Voltage
Power Networks

Aug 50

"Projected Standard of Nominal Voltages for Stationary Electric Networks," Docent L. I. Stolov, Cand Tech Sci, Kazan, M. A. Kogan, Engr, Karaganda Mine Planning Trust

"Elektrichestvo" No 8, pp 85-86

Continues discussions in "Elektrichestvo" No 1, 4, 5, 6, 7, 1950. Criticizes projected standards and suggests improvements.

FDD

167T34

STOLOV, L.I.

Effect of the relationship of time and dynamic moment on the
starting power of d.c. engines. Trudy KAI 25:111-115 '51.

(MLRA 10:7)

(Electric motors, Direct current)

1. BRIGGS, L. I., YACHT
2. USSR (600)
4. Electric Engineering - Study and Teaching
7. Some problems of methodology in teaching a course on electric machinery. Elektrichestvo no. 11, 1952.

9. Monthly List of Russian Accessions, Library of Congress, February 1953. Unclassified.

STOLGV, L. I.

Electrical Engineering Abstracts
May 1954
Machines.

①
1953. The shape of the mechanical characteristics of
small speed motors. L. I. STOLGV, *Elektricheskoe*,
1953, No. 10, 43-4. *In Russian.*
Equations are established giving the relationship
between the current and the speed and between the
couple and the speed, for motors of < 1 kW output.
The calculated curves differ very little from those
obtained experimentally using a method described in
the article.
A. KARLSBAD

TaReYzV, B.M., professor, doktor tekhnicheskikh nauk; GIKIS, A.F., dotsent, kandidat tekhnicheskikh nauk; MEZHLUMOV, A.A., dotsent, kandidat tekhnicheskikh nauk (Baku); STOLOV, L.L., dotsent, kandidat tekhnicheskikh nauk (Kazan'); YUMATOV, A.A., inzhener (Kronshtadt); RAKHIMOV, G.R., dotsent, kandidat tekhnicheskikh nauk; KONSTANTINOV, V.I., inzhener (Moscow); NEYMAN, L.R.; ZAYTSEV, I.A., dotsent, kandidat tekhnicheskikh nauk; LUR'YE, A.G., dotsent, kandidat tekhnicheskikh nauk.

Terminology of theoretical electrical engineering. Elektrichestvo no.2:74-82 P '54. (MLBA 7:2)

1. Vsesoyuznyy zaachnyy energeticheskiy institut (for Tareyev).
2. Rostovskiy institut inzhenerov zheleznodorozhnogo transporta (for Gikis).
3. Sredneaziatskiy politekhnicheskiy institut (for Rakhimov).
4. Chlen-korrespondent Akademii nauk SSSR (for Neyman).
5. Leningradskiy politekhnicheskiy institut im. Kalinina (for Neyman, Zaytsev, Lur'ye). (Electric engineering--Terminology)

STOLOV, L.I.

Selecting electric drives with high electromechanical time constants.
Trudy KAI 28:135-140 '54. (MLRA 10:6)
(Electric driving)

STOLOV, L.I., kand.tekhn.nauk, dots.; KALINKIN, G.I., kand.tekhn.nauk.

Testing micromachines by means of an auxiliary motor. Elektrichestvo
no.1:68-70 Ja '58. (MIRA 11:2)

1.Kazanskiy aviatsionnyy institut.
(Electric motors--Testing)

SOV/144-58-9-6/18

AUTHOR: Stolov, L.I., Cand. of Tech. Sc., Docent, Head of the Chair
for Electrical Engineering and Electrical Machinery
TITLE: On the Shape of the Mechanical Characteristics of Very
Small Asynchronous Motors (O forme mekhanicheskoy
kharakteristiki asinkhronnogo dvigatelya maloy
moshchnosti)

PERIODICAL: Izvestiya Vysshikh Uchebnykh Zavedeniy, Elektromekhanika,
1958, Nr 9, pp 38-44 (USSR)

ABSTRACT: Asynchronous motors with ratings up to a few watts
which have symmetrical windings and are fed from a
symmetrical system of voltages are extensively used
in instruments and control circuits. Usually, in
investigating the mechanical characteristics of
asynchronous motors either the "modulus of the complex
coefficient" A (representing the ratio of the input
voltage of the equivalent circuit to the voltage of the
transverse limb of this circuit in the case of ideal
no-load running) is taken into consideration or it is
assumed that this coefficient equals the real value of
unity. However, in very small asynchronous motors the
relative values of the pure resistances and, to a large
Card 1/4 extent, the relative values of the inductances of the

BOV/144-58-9-6/18

On the Shape of the Mechanical Characteristics of very Small Asynchronous Motors

stator circuit are large compared to the corresponding values of larger asynchronous motors. Therefore, the (negative) argument of the coefficient A reaches in such small motors 30 to 40°, the modulus 2.0 to 2.5 and the current formulae used for calculating the mechanical characteristics of larger asynchronous motors are inapplicable for very small motors. By using the equations of a passive 4-pole

$$\begin{aligned}U_1 &= AU_2 + BI_2 \\ \dot{i}_1 &= CU_2 + DI_2.\end{aligned}\tag{1}$$

it is possible to obtain more general and simple formulae which are suitable also for investigating the performance of very small asynchronous motors. The T-shaped equivalent circuit for the given case is shown in Fig 1. On the basis of the here quoted equations of the passive 4-pole, formulae are derived for calculating the characteristics of very small motors. A comparison

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On the Shape of the Mechanical Characteristics of Very Small
Asynchronous Motors

of the electromagnetic moment vs. slip curve, calculated
according to the here derived equation:

$$M = \frac{0.975 m_1 U_1^2 r_2 s}{n_1 |A r_2 + B s|^2} \quad (4)$$

(curve 1) with that determined experimentally (curve 3)
and that calculated according to the currently used
formula (curve 2) is made in Fig 3, p 42. In the above
quoted formula -

M is the electromagnetic moment, kgm;

m_1 - number of phases of the stator;

n_1 - rotation speed of the magnetic field;

r_2 - rotor resistance;

s - slip;

U_1 - input voltage;

Card 3/4 A and B are complex coefficients.

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On the Shape of the Mechanical Characteristics of very Small
Asynchronous Motors

A formula is also derived for the critical slip, Eq (5),
p 40. The here described method of investigation can
also be extended to small asynchronous motors with
variable parameters; this will be the subject of a
separate paper.

There are 3 figures and 1 Soviet reference.

ASSOCIATION: Kafedra elektrotehniki i elektricheskikh mashin
Kazanskogo aviatsionnogo instituta (Chair for Electrical
Engineering and Electrical Machinery, Kazan Aviation
Institute)

SUBMITTED: July 29, 1958

Card 4/4

8(5)

AUTHOR:

Stolov, L. I., Docent, Candidate of
Technical Sciences

SOV/105-59-1-15/29

TITLE:

Current-Slip-Dependence of an Induction Motor of Small Power
(Zavisimost' toka asinkhronnogo dvigatelya maloy moshchnosti
ot skol'zheniya)

PERIODICAL:

Elektrichestvo, 1959, Nr 1, pp 61-63 (USSR)

ABSTRACT:

This investigation concerns the dependence of the stator current I_1 on the slip s for induction motors with a power of under 1 watt up to a power of a few watts. The motors are fed by a symmetrical voltage system. The static operation method is investigated. The coilings of the stator and rotor of micromotors investigated here cannot meet the conditions of similitude but they are symmetrical. The rotor may be short-circuited or hollow. The equivalent circuit diagram of the micromotor is a four-pole consisting of effective and inductive resistances and feeding the effective resistance. In these micromotors, the relative effective resistances of the stator circuit and those of the rotor are normally great as compared with the corresponding relative resistances of

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Current-Slip-Dependence of an Induction Motor
of Small Power

SOV/105-59-1-15/29

normal induction machines. It is shown that in the induction micromotor examined here the modulus of the stator current I_1 decreases in a wide range of the slip s according to the formula (2) derived here, at an increase of the slip above zero. The parameters of the four-pole are assumed to be constant. If relation (5) is maintained, the power flow direction through the machine remains the same for a "generator" braking at any negative value of s as for the operation as a motor. These circumstances should be considered in the investigation of heat processes in the induction micromotor. The diagram with the curves marking the law of change of the stator-current modulus by the slip is given as an example. A second diagram shows the calculated and the experimental curve $I_1 I_0 = f(s)$ for a short-circuited induction three-phase micromotor of an automatic device. I_0 is the current in ideal idling at $s = 0$. Both curves diverge only slightly. There are 3 figures.

SUBMITTED: July 26, 1958
Card 2/2

STOLCV, I. I.

33124

O Perekhodnykh Momentakh Pri Neposredstvennom Puske Asinkhronivogo Dvigatelya. Trudy Kazansk. Aviats. In-ta, XXII, 1949, c. 31-35

SO: Letopis' Zhurnal'nykh Statey, Vol. 45, Moskva, 1949

STOLOV, Lev Israelovich, dots., kand.tekhn.nauk

Shape of mechanical characteristics of small induction motors. Izv.
vys.ucheb.zav.; elektromekh. 1 no.9:38-44 ' 58. (MIRA 12:1)

1. Zaveduyushchiy kafedroy elektrotekhniki i elektricheskikh mashin
Kazanskogo aviatsionnogo instituta.
(Electric motors, Induction)

SOV/144-59-1-6/21

AUTHOR: Stolov, L.I., Cand.Tech.Sci., Docent, in charge of the
~~Chair~~

TITLE: The Mechanical Characteristics of a Two-phase Induction
Motor with Asymmetrical Stator Circuit

PERIODICAL: Izvestiya vysshikh uchebnykh zavedeniy,
Elektromekhanika, 1959, Nr 1, pp 35-41 (USSR)

ABSTRACT: The stator circuit of a small two-phase induction motor with squirrel cage or hollow rotor may be asymmetrical either because the actual stator winding is asymmetrical or because a capacitor is connected in one phase of the stator winding. The present article shows a simplified way to construct the mechanical characteristics of a motor with an asymmetrical stator. The method is to treat the machine as a symmetrical motor supplied by a system of voltages such that the currents in the two phases are the same as in the original motor. The equivalent circuits of the two phases of the asymmetrical induction motor are given in Fig 1. The actual motor with asymmetrical stator winding is then assumed to be replaced by a symmetrical motor with the same impedances in the equivalent circuit of each phase but with supply voltages that fulfill the

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SOV/144.59-1-6/21

The Mechanical Characteristics of a Two-phase Induction Motor with Asymmetrical Stator Circuit

conditions of Eq (2). Equations are then derived for the phase voltages and the asymmetry factors. A graphical method of determining the asymmetry factors for the equivalent circuits of the two phases is explained with reference to Fig 2. Having found from expression (3a) the modulae of the positive and negative phase-sequence supply voltages, and substituted them in the expression for the electro-magnetic torque of the symmetrical motor, the resultant torque is found from expression (5), together with expression (6a). A typical example is then given of the construction of the mechanical characteristics of a small 400 c/s hollow-rotor capacitor motor, and the torque/slip curves obtained are plotted in Fig 3. The calculated value of the starting torque was 2.9 g.cm and the experimental value was 2.5 g.cm. An appendix gives the derivation of Eqs (3), (4) and (4a). There are 3 figures and 1 Soviet reference. ✓

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2/3

SOV/144-59-1-6/21

The Mechanical Characteristics of a Two-phase Induction Motor with
Asymmetrical Stator Circuit

ASSOCIATION: Kafedra elektrotekhniki i elektricheskikh mashin,
Kazanskiy aviatsionnyy institut
Card 3/3 (Chair of Electro-technology and Electrical Machines,
Kazan' Aviation Institute)

SUBMITTED: December 26, 1958 ✓

PAGE - 2

The Inter-university Scientific Conference on Electrical Measuring Instruments and on the Instrument Means of Automation

307/119-59-3-11/73

accurate automatic potentiometer-type meters in digital computers
 B. E. Shcherbinin Methods of determination of the dynamic errors
 of a magnetic amplifier. P. P. Grigoriev
 Problems in automatic electric stabilization of extremely low
 frequency in measuring instruments. I. A. Krasovskiy
 G. I. P. Galitskiy: Special types of a. c. components
 B. B. Kuznetsov: Automatic bridges and a. c. components
 called for the control of the parameters of transformers in
 mass production. L. A. Shlyk: Some characteristics of
 magnet induction coils which can be used in measuring
 technique and automation. B. A. Berdyuzov: Stray-current
 procedure and liquid level gauges. E. A. Karipalov: The
 sensitivity of a phase-sensitive commutation indicator for
 a. c. semi-equilibrium bridges. S. F. Boris: The application
 of instruments with magnetic bridges, which permit a suitable
 considerable simplification of the design of automatic
 and the circuitry used in the construction of automatic
 quantities. V. A. Nermis: Methods of increasing the
 sensitivity of surge rate analyzers. P. F. Kvititskiy

Card 4/5

Design of apparatus for measuring vibration (stabilizer
 V. V. Pogromov: Main types of semi-automated stabilizer
 circuitry in automation and control technique. S. S.
 Semakovsky: Properties of measuring amplifiers with
 automatic stabilization. E. P. Sviridov: S. A. Shlyk's
 P. M. Zolotarev: The P. Sviridov's precision commutator
 bridge meter operating according to the polar-coasting
 principle. P. S. Slonitskiy and A. Kozminskiy: Methods of
 measuring the magnetic field strength by means of bimetal
 sensors and transformers operating on the Hall effect
 principle. A resolution was adopted by the closing plenary
 meeting of the Conference, which indicates ways of
 improving and coordinating scientific research work in the
 field of automation, electrical measuring- and computing
 technique.

Card 5/5

~~STOLOV, I. I.~~ kand. tekhn. nauk

Relationship between the current and slip in small induction
motors. Elektrichestvo no.1:61-63 Ja '59. (XTRA 12:5)
(Electric motors, Induction)

9(6)

S/146/59/002/06/007/016
D002/D006

AUTHOR: Stolov, L.I., Candidate of Technical Sciences, Docent

TITLE: Some Characteristics of an Asynchronous Micromotor⁹
and the Determination of the Parameters of its Equi-
valent Circuit₅

PERIODICAL: Izvestiya vysshikh uchebnykh zavedeniy. Priborotroy-
eniye, 1959, Nr 6, pp 49-53 (USSR)

ABSTRACT: This is a general discussion of the characteristics
of a micromotor and the problem of determining the
parameters of its equivalent circuit. Equations for
velocity and mechanical characteristics of micro-
motors with a non-symmetrical stator circuit are
derived, and it is concluded that the method des-
cribed can also be used for motors with asymmetric
circuits. The article was recommended by the Orgkomi-
tet mezhvuzovskoy nauchno-tekhnicheskoy konferentsii

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S/146/59/002/06/007/016
D002/D006

Some Characteristics of an Asynchronous Micromotor and the Determination of the Parameters of its Equivalent Circuit

po elektroizmeritel'nym priboram i tekhnicheskim sredstvam avtomatiki (Orgkomitet of the Intervuz Scientific-Technical Conference on Electro-Measuring Devices and Technical Automation Means). There are 2 graphs and 4 Soviet references.

ASSOCIATION: Kazanskiy aviatsionnyy institut (Kazan' Aviation Institute)

SUBMITTED: February 13, 1959

Card 2/2



SOV/105-59-10-9/25

AUTHOR: Osolov, L. L., Candidate of Technical Sciences, Docent (Kazan')

TITLE: Mechanical Characteristics of a Three-phase Induction Motor With Asymmetrical Stator Circuit

PERIODICAL: Elektrichestvo, 1959, No. 10, pp 47-50 (USSR)

ABSTRACT: The author investigates here the mechanical characteristics of low-power three-phase induction motors with short-circuited rotor and asymmetrical stator circuit. The motors are fed by a symmetrical system of three-phase mains voltages (lineynoye napryazheniye). The stator windings of the investigated motors are symmetrical. The asymmetry of the stator circuit is, however, a result of an additional resistance in the b-phase or two additional resistances in the a- and c-phase. These two cases are investigated here, and the formulas for calculating the resulting torque are deduced. This is exemplified in figure 3 by the mechanical characteristics $M = f(S)$ for a short-circuited three-phase induction motor of 6.5 w as calculated by the above method or according to the formulas deduced here. s - slip. Herefrom it follows that the curves obtained by calculation or experiment are nearly coincident. There are 3 figures.

SUBMITTED: June 5, 1959
Card 1/1

AUTHOR: Stolov, L.I., Docent

SOV/144-59-10-19/20

TITLE: Discussion on 'The Calculation of the Mechanical Characteristics of Miniature Induction Motors' (Elektromekhanika, 1959, Nr 7)

PERIODICAL: Izvestiya vysshikh uchebnykh zavedeniy, Elektromekhanika, 1959, Nr 10, pp 157 - 159 (USSR)

ABSTRACT: This is a contribution to the discussion on an article by Nesgovorova and Kaasik, published in Elektromekhanika, 1959, Nr 7. In their article, these authors had made some critical comments about a previous article by Stolov, who maintains his previous position and points out certain misconceptions of Nesgovorova and Kaasik. There are 1 figure and 1 Soviet reference.

ASSOCIATION: Kazanskiy aviatsionnyy institut (Kazan' Aviation Institute)

SUBMITTED: September 20, 1959

Card 1/1

8 (5)
AUTHOR:

Stolov, L. I., Docent, Candidate of
~~Technical Sciences~~ (Kazan')

S/105/60/000/02/012/024
B007/B008

TITLE:

Induction Micromotor With Hollow Rotor at Anomalous Frequency

PERIODICAL:

Elektrichestvo, 1960, Nr 2, pp 61 - 63 (USSR)

ABSTRACT:

The characteristics for the selection of the feed voltage U according to the frequency f at invariable electromagnetic starting moment M for induction micromotors with a hollow non-magnetic rotor are investigated here. These motors show relatively great effective resistances in stator and rotor and very small inductive resistances of the rotor deviation. It is assumed first that the stator circuits of the motor are symmetrical and the motor is fed by a symmetrical voltage system. The stator circuits of a two-phase induction micromotor with a hollow nonmagnetic rotor are however usually asymmetrical. In the case under review the character of the dependence of the control voltage and mains voltage on the frequency is influenced by the asymmetry of the stator winding of the motor, the asymmetry of the system of feed voltages and the necessity of having to alter the condenser capacitance according to the

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Induction Micromotor With Hollow Rotor at
Anomalous Frequency

S/105/60/000/02/012/024
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frequency. It is shown here that contrary to standard induction motors which operate at variable frequency, the function $U(f)$ does not proceed monotonously in the motors investigated here; the voltage U increases at a strong reduction of f (Fig 3). There are 3 figures and 1 Soviet reference.

SUBMITTED: September 8, 1959



Card 2/2

S/144/60/000/03/010/017
E194/E455

AUTHOR: Stolov, L.I., Candidate of Technical Sciences, Docent,
Head of the Chair for Electrical Engineering and
Electrical Machinery

TITLE: The Dynamics of Transient Processes in a Low-Power
Electric Drive ^A

PERIODICAL: Izvestiya vysshikh uchebnykh zavedeniy, Elektromekhanika,
1960, Nr 3, pp 80-84 (USSR)

ABSTRACT: The dynamics of transient processes in electric drives
with variable moment of inertia has been investigated
previously though without allowing for friction in the
reduction gear, which is important in low-power drives.
In the present article the referred moment of inertia
and the referred static torque are assumed variable and
the drive is assumed to contain a reduction gear of
appreciable friction. The mass of the driven mechanism
is assumed to be concentrated and the friction torque
in the reduction gear between the motor and driven
mechanism is assumed to be a linear function of the
output torque of the reduction gear. Systems of this
type may be divided into three classes, depending on

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S/144/60/000/03/010/017
E194/E455

The Dynamics of Transient Processes in a Low-Power Electric Drive

the nature of the load namely: systems in which the driven mechanism is of constant moment of inertia but the transmission ratio is variable; systems in which the driven mechanism is of variable radius of inertia; and systems in which the mass on the shaft of the driven mechanisms is variable. These three cases are considered in turn and formulae are derived for the motor torque, allowing for friction in the reduction gear and the dynamic torque due to the moment of inertia of the motor rotor. The following equations are derived: for the first case, Eq (4); for the second case, Eq (7); and for the third case, Eq (9). The dynamic equations may be integrated by the usual method of finite increments; the procedure is briefly explained. A numerical example of calculations on a drive of the type described is then given. An appendix gives the derivation of two formulae used in the main article. There are 5 Soviet references.

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S/144/60/000/03/010/017
E194/E455

The Dynamics of Transient Processes in a Low-Power Electric Drive

ASSOCIATION: Kazanskiy aviatsionnyy institut
(Kazan Aviation Institute)

SUBMITTED: January 3, 1959

Card 3/3

Mechanical and Speed Characteristics
of D.C. Micromotors

8/105/60/000/08/10/023
B012/B058

section, that is, for the general case where these characteristics are independent of the type of motor excitation. The relations shown in Figs. 1 and 2 are built up on the basis of these formulas. The speed- and mechanical characteristics for micromotors with various types of excitation are then built up with the aid of these formulas. It is necessary to take the nominal speed n_n of the motor instead of the speed n_{ol} , as well as I_a and M_a ($a = \text{start}$) instead of I_{ai} and M_{ai} . The setup of the characteristics of a micromotor with external excitation is shown next (Fig. 3). The characteristics of the micromotors with permanent magnets are also built up in a similar way. The setup of characteristics of a micromotor with series excitation is dealt with finally. The diagram with the mechanical and speed characteristic of a two-pole micromotor with external excitation is given as an example in Fig. 4. There are 4 figures and 3 Soviet references.

ASSOCIATION: Kazanskiy aviatsionnyy institut (Kazan' Aviation Institute)

SUBMITTED: November 9, 1959

Card 2/2

✓B

Determination of the equivalent circuit parameters
S/L96/62/000/004/015/023
E194/E155

angles of ψ_1 , which is the angle of phase displacement between the stator current I and the voltage U_1 on load (usually at short circuit), and at an angle of ψ_0 , which is the phase displacement angle between the stator current I and the voltage U_{10} with synchronous no-load conditions. Perpendiculars are dropped to the ordinate axis from the ends of the vectors U_1/I and U_{10}/I . To the end of the perpendicular dropped from the end of the vector U_1/I is added a section numerically equal to the stator ohmic resistance r_1 . A straight line is drawn from the origin at an angle

$$\theta = \arctan \frac{n}{m}$$

to the ordinate axis to determine the leakage reactance of the stator winding x_1 from the vector diagram. Then the reactance of the quadrature branch of the equivalent circuit

$$x_{12} = \frac{E_1}{I \cos \theta}$$

and the ohmic resistance of the rotor $r_2 = \frac{x_{12} \cdot S}{\tan \theta}$ are found.

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Determination of the equivalent ... S/196/62/000/004/015/023
E194/E155

where: E is the voltage on the quadrature branch of the equivalent circuit; S is the slip; n and m are segments of straight lines determined from the vector diagram. An example is given of a calculation of the parameters of a two-phase 400-cycle capacitor motor with hollow non-magnetic rotor. The difference between calculated values and test results does not exceed 16%. 2 literature references.

[Abstractor's note: Complete translation.]

Card 3/3

S/105/61/000/012/006/006
E194/E455

AUTHOR: Stolov, L.I., Candidate of Technical Sciences, Docent

TITLE: The influence of asymmetry of stator phase resistance of a miniature induction motor on its characteristics

PERIODICAL: Elektrichestvo, no.12, 1961, 76-80

TEXT: Two- and three-phase miniature motors often operate under asymmetrical conditions, and a motor with asymmetrical phase resistance can be represented by a symmetrical motor with asymmetrical supply; however, a motor with asymmetry of stator phase location cannot be treated in this way if the stator currents are left unchanged. A three-phase star-connected miniature motor is first considered in which one phase contains additional resistance and the following expressions are derived for the phase

$$\begin{aligned} \dot{I}_a &= (1 + N_I) \dot{I}_1; \\ \dot{I}_b &= a(a + N_I) \dot{I}_1; \\ \dot{I}_c &= a(1 + aN_I) \dot{I}_1; \end{aligned} \tag{4}$$

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The influence of asymmetry ...

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E194/E455

$$\begin{aligned} \dot{U}_a &= (1 + N_U)\dot{U}_1 \\ \dot{U}_b &= a(a + N_U)\dot{U}_1 \\ \dot{U}_c &= a(1 + aN_U)\dot{U}_1 \end{aligned}$$

where $a = e^{j\frac{2\pi}{3}}$, $\dot{I}_1 = \dot{U}_1$ - positive phase sequence current and phase voltage

\dot{I}_2, \dot{U}_2 - corresponding negative phase sequence values;

$N_1 = \dot{I}_2/\dot{I}_1$ - degree of current asymmetry;

N_U - the corresponding voltage asymmetry on the positive and negative phase sequence impedances.

The method is easily extended to three-phase motors with additional resistance in two phases and to two-phase motors.

The influence of asymmetry on starting torque is then considered and the following expressions are obtained:

$$\Delta \mu_1 = 1 - \mu_1 = 1 - q_1 = \frac{3(k^2 - 1)}{(2k + 1)^2}$$

(10) ✓

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The influence of asymmetry ...

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E194/E455

$$\mu_2 = q_2 = \left(\frac{k-1}{2k+1} \right)^2$$

where μ_1 - the positive phase sequence torque, μ_2 - the negative phase sequence torque, k - an asymmetry factor.

On the basis of the above equations, characteristic curves may be drawn and from examination of them the following conclusions are drawn: the reduction in the magnitude of the positive phase sequence torque that results from asymmetry has a much greater effect on the resultant starting torque than has the setting up of a negative phase sequence torque; and even with a considerable asymmetry factor, the asymmetry of currents and voltages is not great. It is also concluded that if an inductance is connected in one stator phase of a miniature motor, the speed in the working range of slip is lower and the mechanical characteristics are better than when the inductance is distributed uniformly between the three phases. It is accordingly recommended to use a saturating choke in one phase only of the stator circuit of small induction motors for speed control. There are 6 figures and
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The influence of asymmetry ...

S/105/61/000/012/006/006
E194/E455

1 Soviet bloc reference

ASSOCIATION Kazanskiy aviatsionnyy institut
(Kazan Aviation Institute)

SUBMITTED July 7, 1961



Card 4/4

STOLOV, L.I., kand.tokhn.nauk, dotsent (Kazan)

Problem concerning the determination of the equivalent parameters
of a small asynchronous motor. Elektrichestvo no.5:87-89 My '62.

(MIRA 15:5)

(Electric motors, Induction)
(Equivalent circuits)

STOLOV, L.I., kand.tekhn.nauk, dotsent (Kazar.)

Calculation of transient processes of a small asynchronous
motor. Elektrichestvo no.8:76-81 Ag '62. (MIRA 15:7)
(Electric motors, Induction)

BEFALYAN, Stepan Davidovich; LONCHOSOV, V.Yu., prof., retsenzent;
STOLOV, L.I., dots., retsenzent; ATABEKOV, G.I., red.;
BYCHKOV, D.V., dots., red.; FRIDKIN, L.M., tekhn. red.

[Theoretical principles of electrical engineering in three
parts] Teoreticheskie osnovy elektrotehniki [v trekh
chastiakh]. Moskva, Gosenergoizdat. Pt.3. [Electromagnetic
field] Elektromagnitnoe pole. 1963. 110 p.

(MIRA 16:12)

(Electric engineering) (Electromagnetic fields)

STOLOV, L.I., kand.tekhn.nauk, dotsent

Thermal design of electrical circuits with variable resistance.
Izv. vys. ucheb. zav.; energ. 6 no.4:22-28 Ap '63. (MIRA 16:5)

1. Kazanskiy aviatsionnyy institut. Predstavlena kafedroy
elektrotekhniki i elektricheskikh mashin.
(Electric motors) (Electric networks)

L 15129-65 EWT(1)/EWT(m) JD
ACCESSION NR: AT4047558

8/2529/83/000/075/0003/0014

7
B

AUTHOR: Stolov, I. I. (Decent)

TITLE: The dynamic mechanical characteristics of a low-power asynchronous motor

SOURCE: Kazan. Aviatsonnyy institut. Trudy*, no. 75, 1963. Aviatsonnyye pribory* i avtomaty* (Aeronautical instruments and automatic equipment), 3-14

TOPIC TAGS: asynchronous motor, low power motor, Kirchhoff law, Helmholtz Thevenin theorem, braking moment

ABSTRACT: The author notes that in the investigation of the electromechanical transient modes of an asynchronous machine, three differential equations must be jointly considered. Two of these represent Kirchhoff's law for transient processes in the stator and rotor circuits, while the third is the equation for the dynamics of the drive. It is indicated that an equation system of this type, with variable angular velocity in the rotation of the rotor ω , can be solved by the method of consecutive intervals (with the continuous changes replaced by step-wise changes and assuming that in each time interval $\omega = \text{const.}$ and the initial conditions are non-zero), but that this technique entails cumbersome computations. Another approach is presented in this article. Kirchhoff's law for the stator circuit is represented in the Laplace form. The rotor circuit is replaced by an immobile circuit.

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ACCESSION NR: AT4047558

moving from the natural coordinate axes of the rotor to the stator axes. Stator and rotor windings, as well as the feed voltage system, are considered balanced, and no allowance is made for upper harmonics. The author notes that in low-power motors the relative values of the active resistances of the stator circuit, and occasionally of the rotor circuit, are extremely large. In comparison, the corresponding scattering inductances are small and the rapidly attenuating free current components disappear in the course of negligibly small time intervals. For this reason, in his construction of the dynamic mechanical characteristics of the low-power motor, the author investigates the character of the fading of the free currents and flows by means of a transient mode displacement arrangement, with the scattering inductances disregarded. The Helmholtz-*Thevenin* theorem is used. The displacement theorem employed was borrowed from the work of Ye. Ya. Kazovskiy (Nekotorye voprosy perekhodnykh protsessov v mashinakh peremennogo toka. GEI, 1953). The author develops the static, dynamic and mechanical characteristics of a low-power asynchronous engine, as well as the initial braking moment as a function of the rotational velocity of the rotor, and presents these parameters in graph form. An example is given in the article and a technique is briefly outlined whereby the resultant characteristics can be further refined. Orig. art. has: 6 figures and 16 formulae.

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L 15129-65

ACCESSION NR: AT4047568

ASSOCIATION: Kazanskiy aviatsionnyy institut (Kazan Aviation Institute)

SUBMITTED: 01Oct81

ENCL: 00

SUB CODE: PR, AC

NO REF SOV: 005

OTHER: 000

Card 3/3

L 20781-65 EWT(d)/EWT(1) Po-4/Pq-4/Pg-4/Pr-4/P1-4 IJF(c) EC
ACCESSION NR: AP5003792 3/0144/64/000/009/1082/1087

AUTHOR: Stolov, L. I.

TITLE: Calculation of the characteristics of a two-phase asynchronous micromotor with asymmetric distribution of the phases of the stator winding

SOURCE: IVUZ. Elektromekhanika, no. 9, 1964, 1082-1087

TOPIC TAGS: electric motor, miniature electric equipment, electric rotating equipment part

Abstract: In general, the discussion of the motion of a two-phase asynchronous micromotor with an asymmetric stator circuit may be carried out by resolving the pulsating mmf of each phase into rotating mmf's. Often, the above mentioned asymmetry of the stator circuit causes a specially asymmetric distribution of the phases of the stator winding. The author shows that the spatial asymmetry of the phases may be reduced to an asymmetry of the resistances of the stator circuit phases and presents an appropriate method for the calculation of the micromotor characteristics using the conventional asymmetry coefficients of the equivalent circuit resistances.

Orig. art. has: 2 figures, 7 formulas, 1 graph.

ASSOCIATION: none

SUBMITTED: 01Feb64

ENCL: 00

SUB CODE: EK

NO REF SOV: 003

OTHER: 000

JPRS

Card 1/1

ATABEKOV, Grigoriy Iosifovich; LOMONOSOV, V.Yu., prof., rezensent;
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